

Mech 2.1

1.1 the angular displacement of the motor shaft is

$$\theta(t) = 241t - 20.2t^2 - 1.51t^3.$$

the angular velocity is

$$\omega(t) = \dot{\theta}(t) = 241 - 40.4t - 4.53t^2$$

and the angular acceleration is

$$\alpha(t) = \ddot{\theta}(t) = -40.4 - 9.06t.$$

1.1. the angular velocity is zero at

$$\omega(t) = 241 - 40.4t - 4.53t^2 = 0$$

$$\Rightarrow t = \dots = \underline{4.09 \text{ s}}$$

1.2. the angular acceleration at the instant when $\omega = 0$ is

$$\alpha(4.09) = -40.4 - 9.06(4.09)$$

$$\Rightarrow \alpha(4.09) = \underline{-77.5 \text{ rad s}^{-2}}.$$

1.3. the angular displacement after 4.09 s is

$$\theta(4.09) = 241(4.09) - 20.2(4.09)^2 - 1.51(4.09)^3 \\ = 544.5 \text{ rad.}$$

which implies that the number of revolutions is $\frac{\theta(4.09)}{2\pi} = \frac{544.5}{2\pi} = 86.7 \text{ rad.}$

(or 86 complete revolutions).

1. 4. the angular velocity of the shaft
at $t=0$ is

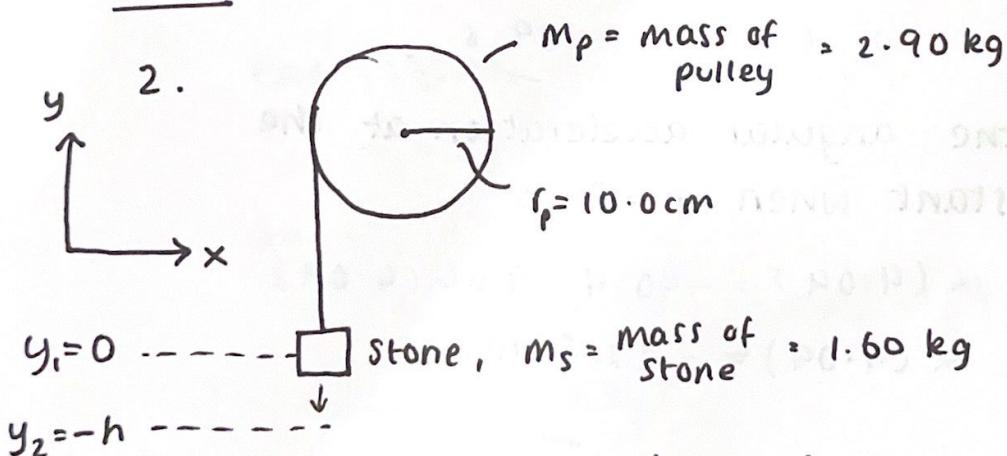
$$\omega(0) = 241 \text{ rad s}^{-1}$$

1. 5. the average angular velocity is

$$\omega_{\text{av.}} = \frac{\theta(t_2) - \theta(t_1)}{t_2 - t_1}$$

$$= \frac{544.5 - 0}{4.09 - 0}$$

$$\Rightarrow \omega_{\text{av.}} = 133 \text{ rad s}^{-1}$$



apply conservation of energy. For the uniform solid disc, its kinetic energy under rotational motion is

$$T_p = T_{\text{pulley}} = \frac{1}{2} I_p \omega^2,$$

where $I_p = \frac{1}{2} M_p r_p^2$ is the moment of inertia and ω is the angular velocity of the pulley. The speed of the stone is related to the angular velocity of the

pulley via

$$v = r_p \omega.$$

- the moment of inertia of the pulley is

$$I_p = \frac{1}{2} m_p r_p^2 = \frac{1}{2} (2.90) (0.100)^2$$

$$\Rightarrow I_p = 0.0145 \text{ kg m}^2$$

- the kinetic energy of the pulley is given as $T_p = 3.30 \text{ J}$.

- the angular velocity of the pulley is

$$\omega = \sqrt{\frac{2 T_p}{I_p}} = \sqrt{\frac{2 (3.30)}{0.0145}} = 21.3 \text{ rad s}^{-1}.$$

- the stone thus has speed

$$v_s = r_p \omega = 0.100 \cdot 21.3 = 2.13 \text{ ms}^{-1}$$

so its kinetic energy is

$$T_{\text{stone}} = T_s = \frac{1}{2} m_s v_s^2 = \frac{1}{2} (1.60) (2.13)^2$$

$$\Rightarrow T_s = 3.63 \text{ J}.$$

- we have all our kinetic energies, so apply constⁿ of energy:

$$T_i + U_i = T_f + U_f \quad \begin{cases} i = \text{initial, } t=0 \\ f = \text{final, at height h} \end{cases}$$

$$= 0 \text{ as released from rest } (T_i = 0) \quad = T_p + T_s + m_s g (-h).$$

and at 0 height
($U_i = 0$)

hence

$$0 = T_p + T_s + mg(-h)$$
$$\Rightarrow h = \frac{T_p + T_s}{mg}$$
$$\Rightarrow h = \frac{3.30 + 3.63}{1.60(9.81)} = 0.442 \text{ m}$$

2.2. the pulley's kinetic energy T_p accounts for

$$\left[\frac{T_p}{T_p + T_s} = \frac{3.30}{3.30 + 3.63} = 0.476 \right]$$

47.6 % of the total kinetic energy.

3.1 if we scale the length scales by f , the volume & mass are scaled by f^3 . the moment of inertia scales as

$$I \rightarrow \sum_i [m_i (f^3) \cdot r_i (f)^2] = (\sum_i m_i r_i) f^5 .$$

$\Rightarrow I$ scales as f^5 .

3.2. the scaling factor is 48 as we are increasing the lengths.

Since the rotational kinetic energy is directly proportional to the moment of inertia, $T \propto I$, $T_{\text{true}} = f^5 T_{\text{model}}$

$$\Rightarrow T_{\text{true}} = 48^5 (2.50) = 6.4 \times 10^8 \text{ J.}$$